

The terrestrial laser scanner system *RIEGL*® LMS-Z390i consists of a highly accurate and fast 3D scanner, the accompanying operating and processing software RiSCAN PRO, and a calibrated and accurately orientated and mounted high-resolution digital camera.

The system provides data which lends itself to automatic or semiautomatic processing of scan data and image data to generate products such as textured triangulated surfaces or orthophotos with depth information.

The *RIEGL* LMS-Z390i is a rugged and fully portable sensor especially designed for the rapid and accurate acquisition of high-quality three dimensional images, providing a unique and unrivalled combination of a wide field-of-view, high accuracy, and fast data acquisition.

A standard Windows notebook and the bundled software package RiSCAN PRO enable the user to instantly acquire high-quality 3D data in the field and provide a variety of registration, post processing, 3D data viewing and export functions .

Architecture & Facade Measurement
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As-Built Surveying
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City Modelling
Topography

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System Key Performance Data



Scanner Hardware LMS-Z390i

allows high-speed, high resolution and accurate 3D measurements

Ranges up to 400 m @ Laser Class 1

Repeatability up to 2 mm

Measurement rates up to 11000 pts/sec

Field of View up to 80° x 360°

TCP/IP data interface, allowing easy wireless data

transmission

Operable with any standard PC or Notebook

Fully portable, rugged & robust

Software RiSCAN PRO

RIEGL software package for scanner operation and data processing

Data archiving using a well-documented tree structure in the XML file format

Object VIEW / INSPECTOR for intelligent data viewing

and feature extraction

Straightforward Global Registration

Interfacing to Post Processing

Software



Camera (optional)

provides high resolution calibrated color images

NIKON D700 / NIKON D300(s) / NIKON D200:

D300(s): 12.3 Megapixel

D700: 12.1 Megapixel, Nikon FX format

D200: 10.2 Megapixel

USB interface

The combination of the key components <u>Scanner</u>, <u>Software</u> and <u>Camera</u> results in

Automatic generation of high resolution textured meshes

Automatic generation of 3D orthophotos

Online position and distance measurements

Photorealistic 3D reconstruction

Online setting of any virtual point of view

Exact identification of details

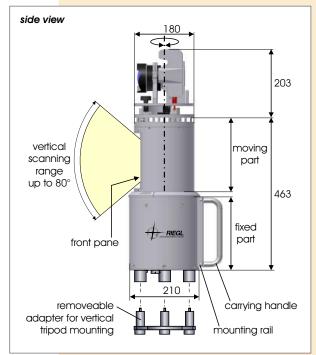
Principle of Scanner Operation & Dimensional Drawings

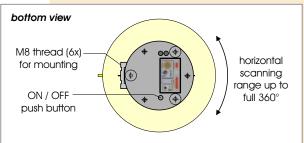
The range finder electronics of the 3D laser scanner *RIEGL* LMS-Z390i are optimized in order to meet the requirements of high speed scanning (high laser repetition rate, fast and highly accurate signal processing, and high speed data interface).

The vertical deflection ("line scan") of the laser beam is realized by a polygon with a number of reflective surfaces. For high scanning rates and/or a vertical scan angle of up to 80° , the polygonal mirror continuously rotates at an adjustable speed. For slow scanning rates and/or small scanning angles, it linearly oscillates up and down. The horizontal scan ("frame scan") is realized by rotating the complete optical head up to 360° .

Scandata: RANGE, ANGLE, SIGNAL AMPLITUDE, and optional TIMESTAMP are transmitted to a laptop via TCP/IP Ethernet Interface. Camera data is fed into the same laptop via USB/firewire interface.

The RiSCAN PRO software allows the operator to perform a large number of tasks including sensor configuration, data acquisition, data visualization, data manipulation, and data archiving. RiSCAN PRO runs on the platforms Windows XP Professional, Windows VISTA Professional, and Windows 7 Professional.

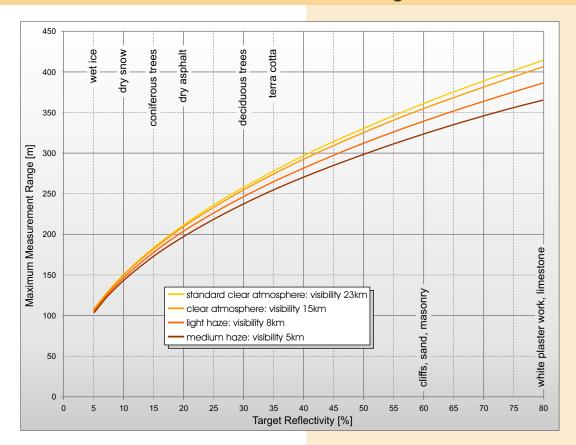




Maximum Measurement Range RIEGL LMS-Z390i

The following conditions are assumed:

Flat target larger than footprint of laser beam, perpendicular angle of incidence, average brightness



Technical Data 3D Scanner Hardware RIEGL LMS-Z390i

Laser Product Classification

Class 1 Laser Product according to IEC60825-1:2007

The following clause applies for instruments delivered into the United States: Compiles with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.



Rangefinder Performance

Max. Measurement Range ¹⁾
for natural targets, 80 %
for natural targets, 10 %

Minimum Range for natural targets for reflector targets Accuracy ^{2) 4)} Repeatability ^{3) 4)}

Measurement Rate
Laser Wavelength

Beam Divergence 5)

 Typical values under average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter and near to perpendicular angle of incidence of the laserbeam. In bright sunlight, the operational range is considerably shorter than under an overcast sky.

Accuracy is the degree of conformity of a measured quantity to its actual (true) value. up to 400 m

1 m 2 m 6 mm

4 mm (single shot), 2 mm (averaged)

up to 11000 pts/sec @ low scanning rate (oscillating mirror) up to 8000 pts/sec @ high scanning rate (rotating mirror)

near infrared typ. 0.3 mrad

3) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

 One sigma @ 50 m range under RIEGL test conditions and vertical scanner setup position.

 0.3 mrad correspond to 30 mm increase of beamwidth per 100 m of range.

Scanner Performance

Vertical (Line) Scan

Scan Angle Range Scanning Mechanism

Scan Speed

Angular Stepwidth

between consecutive laser shots Angle Measurement Resolution

Horizontal (Frame) Scan

Scan Angle Range

Scanning Mechanism

Scan Speed 7

Angular Stepwidth

between consecutive scan lines Angle Measurement Resolution

Inclination Sensors
Internal Sync Timer

0° to 80°

rotating / oscillating mirror

1 scan/sec to 20 scans/sec @ 80° scanning range

0.002° 0.2°

 0.001°

 0° to 360°

rotating optical head

0.01°/sec to 15°/sec

0.002° 0.75°

0.001°

integrated, for vertical scanner setup position 8)

8) Specifications to be found in separate datasheet.

option for real-time synchronized time stamping of scan data 81

6) Selectable via Ethernet Interface or RS232.

 7) Horizontal scan can be disabled, providing 2D-scanner operation.

General Technical Data

Interfaces: for configuration & data output

for configuration for data output

Power Supply Input Voltage

Power Consumption

Current Consumption @ 12 V DC

@ 24 V DC

Main Dimensions

Weight

Temperature Range Protection Class TCP/IP Ethernet, 10/100 MBit/sec

RS 232, 19.2 kBd

ECP standard (enhanced capability port) parallel

12 - 28 V DC

typ. 55 W max. 68 W typ. 4.6 A max. 5.7 A typ. 2.3 A max. 2.85 A

463 mm x 210 mm (length x diameter)

approx. 15 kg

 0° C to $+40^{\circ}$ C (operation), -10° C to $+50^{\circ}$ C (storage)

IP64, dust and splash-proof



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